

6 Determinant

Definition 1 (Determinant). Let $A \in \mathbb{R}^{n \times n}$ be a matrix with entries $a_{i,j}$.

- If $n = 1$, then $A = (a_{1,1})$ and we define

$$\det(A) = a_{1,1}.$$

- If $n \geq 2$, we define

$$\begin{aligned}\det(A) &= a_{1,1} \det(A_1) - a_{2,1} \det(A_2) + \dots + (-1)^{n-1} a_{n,1} \det(A_n) \\ &= \sum_{i=1}^n (-1)^{i-1} a_{i,1} \det(A_i),\end{aligned}$$

where A_i is obtained from A by deleting the first column and i -th row of A .

$n = 2$:

$$\begin{aligned}\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} &= a \det(A_1) - c \det(A_2) \\ &= a \det(d) - c \det(b) \\ &= ad - bc\end{aligned}$$

Theorem 2 (Determinant & elementary row transformations). Let $A, B \in \mathbb{R}^{n \times n}$ such that B is obtained from A by an elementary row transformation.

- If B is obtained from A by swapping two rows (or two columns), then $\det(B) = -\det(A)$.
- If B is obtained from A by multiplication of a row (or column) with a real number c , then $\det(B) = c \det(A)$.
- If B is obtained from A by adding a multiple of a row (or column) to another row (or column), then $\det(B) = \det(A)$.

Definition 3 (Transpose). The transpose A^T of an $(m \times n)$ -matrix A with entries $a_{i,j}$ is the $(n \times m)$ -matrix B with entries $b_{i,j} = a_{j,i}$.

Theorem 4 (Invertible matrices & linear systems). Let $A \in \mathbb{R}^{n \times n}$. Then the following are equivalent.

- (i) A is invertible.
- (ii) For every $\mathbf{b} \in \mathbb{R}^n$: $A\mathbf{x} = \mathbf{b}$ has a unique solution.
- (iii) A has rank n .
- (iv) $\det A \neq 0$.

Theorem 5 (Properties of the determinant). Let $A \in \mathbb{R}^{n \times n}$ with entries $a_{i,j}$ and let $B, C \in \mathbb{R}^{n \times n}$.

- (i) If $A = BC$, then $\det(A) = \det(B) \det(C)$.
- (ii) $\det(A^T) = \det(A)$.
- (iii) If

$$A = \begin{pmatrix} A_1 & B \\ 0_{n-k,k} & A_2 \end{pmatrix}$$

with $A_1 \in \mathbb{R}^{k \times k}$, $A_2 \in \mathbb{R}^{(n-k) \times (n-k)}$ and $B \in \mathbb{R}^{k \times (n-k)}$, then

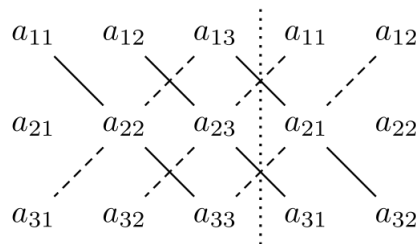
$$\det(A) = \det(A_1) \det(A_2).$$

- (iv) If A is in simple form, then

$$\det(A) = a_{1,1}a_{2,2} \cdot \dots \cdot a_{n,n}.$$

- (v) Sarrus' rule is a method and a memorization scheme to compute the determinant of a 3×3 matrix.

$$\det \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} = a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} - a_{13}a_{22}a_{31} - a_{11}a_{23}a_{32} - a_{12}a_{21}a_{33}.$$



Write out the first 2 columns of the matrix to the right of the 3rd column, so that you have 5 columns in a row. Then add the products of the diagonals going from top to bottom and subtract the products of the diagonals going from bottom to top.

Corollary 6 (Laplace's formula).

$$\det(A) = \sum_{i=1}^n (-1)^{i+j} a_{i,j} \det(A_{ij}),$$

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where A_{ij} is obtained from A by deleting the j -th column and i -th row of A .

Theorem 7 (Cramer's rule). Let $A \in \mathbb{R}^{n \times n}$ invertible with column vectors a_i for $i = 1, \dots, n$ and $b \in \mathbb{R}^n$. Then the unique solution vector $\mathbf{x} = (x_1, \dots, x_n)^T$ of the system $A\mathbf{x} = \mathbf{b}$ can be calculated in the following way:

$$x_i = \frac{1}{\det(A)} \det(a_1, \dots, a_{i-1}, b, a_{i+1}, \dots, a_n), \text{ for } i = 1, \dots, n.$$

Corollary 8. The Inverse of a 2×2 matrix can be computed as follows:

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \Rightarrow A^{-1} = \frac{1}{\det(A)} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$