

Analytic geometry

Definition 1 (Scalar product). *The scalar product of two column vectors $\mathbf{x} = (x_1, x_2, \dots, x_n)^T$ and $\mathbf{y} = (y_1, y_2, \dots, y_n)^T$ is defined as*

$$\mathbf{x} \cdot \mathbf{y} = x_1y_1 + x_2y_2 + \dots + x_ny_n.$$

The dot \cdot is usually omitted.

Theorem 2 (Properties of scalar product & length). *If $\mathbf{x}, \mathbf{y}, \mathbf{z} \in \mathbb{R}^n$ and $s \in \mathbb{R}$, then*

(i) $(s\mathbf{x})\mathbf{y} = s(\mathbf{x}\mathbf{y}),$

(ii) $\mathbf{x}\mathbf{y} = \mathbf{y}\mathbf{x},$

(iii) $(\mathbf{x} + \mathbf{y})\mathbf{z} = \mathbf{x}\mathbf{z} + \mathbf{y}\mathbf{z},$

(iv) $|\mathbf{x}| \geq 0$ and $|\mathbf{x}| = 0$ if and only if $\mathbf{x} = \mathbf{0},$

(v) $|s\mathbf{x}| = |s||\mathbf{x}|,$

(vi) $|\mathbf{x}\mathbf{y}| \leq |\mathbf{x}||\mathbf{y}|,$

(vii) $||\mathbf{x}| - |\mathbf{y}|| \leq |\mathbf{x} + \mathbf{y}| \leq |\mathbf{x}| + |\mathbf{y}|.$

Definition 3 (Orthogonality). *Two vectors $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ are orthogonal or perpendicular, denoted by $\mathbf{x} \perp \mathbf{y}$, if $\mathbf{x}\mathbf{y} = 0$.*

Definition 4 (Straight line). *Let $\mathbf{a}, \mathbf{b} \in \mathbb{R}^2$ or \mathbb{R}^3 with $\mathbf{b} \neq \mathbf{0}$. The straight line through \mathbf{a} with direction \mathbf{b} is the set*

$$L = \{\mathbf{x} = \mathbf{a} + \lambda\mathbf{b}: \lambda \in \mathbb{R}\}.$$

This description is called parametric form, and \mathbf{b} is called the direction vector of L .

Theorem 5 (Alternative descriptions of lines). *(i) If $\mathbf{a} \neq \mathbf{b}$ are two points in \mathbb{R}^2 or \mathbb{R}^3 , then the unique straight line through both of them is given by*

$$L = \{\mathbf{x} = \mathbf{a} + \lambda(\mathbf{b} - \mathbf{a}): \lambda \in \mathbb{R}\}.$$

(ii) If $L \subset \mathbb{R}^2$ is a straight line, there exists a vector $\mathbf{n} \in \mathbb{R}^2$ with $|\mathbf{n}| = 1$ and a number $d \geq 0$ such that

$$L = \{\mathbf{x} \in \mathbb{R}^2: \mathbf{n} \cdot \mathbf{x} = d\}.$$

This description is called HESSE's normal form, and \mathbf{n} is called the normal vector of L .

Definition 6 (Plane). *Let $\mathbf{a}, \mathbf{b}, \mathbf{c} \in \mathbb{R}^2$ or \mathbb{R}^3 such that $\{\mathbf{b}, \mathbf{c}\}$ is linearly independent. The plane through \mathbf{a} spanned by \mathbf{b} and \mathbf{c} is the set*

$$\begin{aligned} P &= \{\mathbf{x} = \mathbf{a} + \mathbf{y}: \mathbf{y} \in \text{span}\{\mathbf{b}, \mathbf{c}\}\} \\ &= \{\mathbf{x} = \mathbf{a} + \lambda\mathbf{b} + \mu\mathbf{c}: \lambda, \mu \in \mathbb{R}\}. \end{aligned}$$

This description is called parametric form, and \mathbf{b} and \mathbf{c} are called the spanning vectors of P .

Theorem 7 (Alternative descriptions of planes). (i) If $\mathbf{a}, \mathbf{b}, \mathbf{c}$ are three points in \mathbb{R}^3 that do not lie on a line (i.e., $\{\mathbf{b} - \mathbf{a}, \mathbf{c} - \mathbf{a}\}$ is linearly independent), then the unique plane through them is given by

$$P = \{\mathbf{x} = \mathbf{a} + \lambda(\mathbf{b} - \mathbf{a}) + \mu(\mathbf{c} - \mathbf{a}) : \lambda, \mu \in \mathbb{R}\}.$$

(ii) If $P \subset \mathbb{R}^3$ is a plane, there exists a vector $\mathbf{n} \in \mathbb{R}^3$ with $|\mathbf{n}| = 1$ and a number $d \geq 0$ such that

$$P = \{\mathbf{x} \in \mathbb{R}^3 : \mathbf{n} \cdot \mathbf{x} = d\}.$$

This description is called HESSE's normal form, and \mathbf{n} is called the normal vector of P .

Theorem 8 (Distance). Let M be a line in \mathbb{R}^2 or a plane in \mathbb{R}^3 with Hesse's normal form $P = \{\mathbf{x} \in \mathbb{R}^3 \text{ resp. } \mathbb{R}^2 : \mathbf{n} \cdot \mathbf{x} = d\}$ and let \mathbf{x}_0 be a point in \mathbb{R}^2 or \mathbb{R}^3 , respectively. The distance between \mathbf{x}_0 and M is given by

$$\text{dist}(\mathbf{x}_0, M) = \min_{\mathbf{y} \in M} |\mathbf{x}_0 - \mathbf{y}| = |\mathbf{n} \cdot \mathbf{x}_0 - d|.$$